# **Superconditioning**

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**Theorem.** P' comes from P by conditionalization if and only if there exists a  $B \ge 1$  such that

$$P'(\omega) \leq BP(\omega)$$



# **Takeaway**

In principle, the shift from P to P' can be represented by conditionalizing on E.

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The conditioning proposition E is an idealization that does not (necessarily) stand for something the agent can express.

That a superconditioning space exists is a plausible **necessary condition** for the shift to be a **learning event**.

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- A shift from a prior to a set of posteriors. This provides insights about the reflection principle.
- A shift from a prior to two ore more distinct sets of posteriors.
  This speaks to the common prior assumption and a model of time-slice rationality.

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- for each  $\omega \in \Omega$  there is an  $E_{\omega} \in \mathfrak{A}$  and  $P(\omega) = Q(E_{\omega})$ ;
- there is a partition  $E_1, \ldots, E_n \in \mathfrak{A}$  of  $\Lambda$  such that

$$P_i(\omega) = Q(E_\omega \mid E_i) \quad \text{if } Q(E_i) > \text{o.}$$

# Superconditioning

**Theorem.** The shift from P to  $P_1, \ldots, P_n$  can be embedded in a conditioning model if and only if there exist constants  $0 \le B_1, \ldots, B_n \le 1, \sum_i B_i = 1$  such that for all  $\omega \in \Omega$ ,

$$P(\omega) = \sum_i B_i P_i(\omega).$$

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In this case  $B_i = P(A_i)$  and

$$P(\omega) = \sum_{i} P(A_i) P_i(\omega).$$

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Since the generalized reflection principle doesn't require priors over posteriors, it applies to (genuinely) diachronic shifts.

If we take being representable in a superconditioning space as a necessary condition for a shift to be a learning event, then the reflection principle is a necessary condition as well.

Consider two distinct shifts from a prior P to posteriors  $P_{11}, \ldots, P_{1n}$  and  $P_{21}, \ldots, P_{2m}$ .

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The shifts from P to  $P_{11}, \ldots, P_{1n}$  and  $P_{21}, \ldots, P_{2m}$  can be **embedded** in a **conditioning model** if there exists a probability space  $(\Lambda, \mathfrak{A}, Q)$  such that

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- for each  $\omega \in \Omega$  there is an  $E_{\omega} \in \mathfrak{A}$  and  $P(\omega) = Q(E_{\omega})$ ;
- there is a partition  $E_{11}, \ldots, E_{1n} \in \mathfrak{A}$  of  $\Lambda$  such that

$$P_{1i}(\omega) = Q(E_{\omega} \mid E_{1i}) \text{ if } Q(E_{1i}) > 0;$$

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• there is a partition  $E_{21}, \ldots, E_{2m} \in \mathfrak{A}$  of  $\Lambda$  such that

$$P_{2j}(\omega) = Q(E_{\omega} \mid E_{2j}) \text{ if } Q(E_{2j}) > 0.$$

# Superconditioning

**Theorem.** The shifts from P to  $P_{11},\ldots,P_{1n}$  and  $P_{21},\ldots,P_{2m}$  can be embedded in a conditioning model if and only if there exist constants  $0 \le B_{11},\ldots,B_{1n} \le 1$  and  $0 \le B_{21},\ldots,B_{2m} \le 1$  such that  $\sum_i B_{1i} = \sum_j B_{2j} = 1$  and for all  $\omega \in \Omega$ ,

$$P(\omega) = \sum_i B_{1i} P_{1i}(\omega) = \sum_j B_{2j} P_{2j}(\omega).$$

### **Common prior**

We say that  $P_{11}, \ldots, P_{1n}$  and  $P_{21}, \ldots, P_{2m}$  have a **common prior** if there is a P such that the shift from P to  $P_{11}, \ldots, P_{1n}$  and  $P_{21}, \ldots, P_{2m}$  can be embedded in a conditioning model.

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**Corollary.**  $P_{11}, \ldots, P_{1n}$  and  $P_{21}, \ldots, P_{2m}$  have a common prior if and only if the intersection of their convex spans is nonempty.

# Game theory

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The result shows that for a common prior to exist the players' posteriors must agree to some extent.

# Time-slice epistemology

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According to Williamson, your current credences are not constrained by your past credences, but by your current evidence. At any given time, your current credence in a proposition should match the prior conditional probability of that proposition, conditional on your current evidence. The prior probability distribution is a distinguished measure of "something like the intrinsic plausibility of hypotheses prior to investigation" [...], and your current evidence is just your current knowledge [..]. Since knowledge is not necessarily cumulative for rational agents, this proposal answers challenges involving rational memory loss. Since your current mental states include your current knowledge, this proposal advances timeslice epistemology.

Moss, Time-slice rationality and action under indeterminacy

### Final extension

 $P_1$  and  $P_2$  come from P by conditionalization if there exists a probability space  $(\Lambda, \mathfrak{A}, Q)$  such that

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- there is an  $E_2 \in \mathfrak{A}$  such that  $Q(E_2) > 0$  and  $P_2(\omega) = Q(E_\omega \mid E_2)$ .

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**Theorem.**  $P_1$  and  $P_2$  come from P by conditionalization if and only if there exists a  $B \ge 1$  such that, for all  $\omega \in \Omega$ ,

$$P_1(\omega), P_2(\omega) \leq BP(\omega).$$

# **Takeaway**

This condition does not generate any interesting dynamic coherence between  $P_1$  and  $P_2$ :

- $P_1(E) = 1$  and  $P_2(E) = 0$ ;
- $P_1(E) = 0$  and  $P_2(E) = 1$ .

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- $P_1(E) = 0$  and  $P_2(E) = 1$ .

In the rich framework of sets of posteriors, the two time slices cannot be fully divorced from each other: an underlying prior exists only if their convex spans overlap.

# Thank you!

